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On the stationary flow of viscous incompressible fluids past an obstacle

(Joint work with Hyunseok Kim and Hideo Kozono)

Overview



Introduction

Weak Solutions

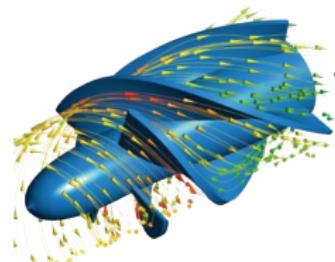
Main Result

Comments on the proof

Situation:

Viscous, incompressible fluid surrounding
a moving obstacle.

1. Rotation with constant speed and axis
2. Axis of rotation parallel to translation
3. Translation with constant speed or
fluid velocity at ∞ is constant



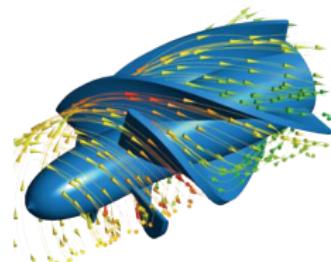
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The governing equations are given by

The Navier-Stokes equations



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$$u_t - \Delta u + u \cdot \nabla u + \nabla \pi = \operatorname{div} F \quad \text{in } \Omega(t), t > 0$$

$$\operatorname{div} u = 0 \quad \text{in } \Omega(t), t > 0$$

$$u(x, t) = Mx \quad \text{on } \partial\Omega(t), t > 0$$

$$u(x, t) \rightarrow U \quad \text{for } |x| \rightarrow \infty$$

u : velocity, π : pressure, “ $U = u(\infty)$ ”

The Navier-Stokes equations



Transformation $x \rightsquigarrow e^{Mt}x$ and $u \rightsquigarrow e^{Mt}(u - U)$ leads to the system

$$\begin{aligned} u_t - \Delta u + u \cdot \nabla u + \nabla \pi &= \operatorname{div} F && \text{in } \Omega, t > 0 \\ + U \cdot \nabla u - (Mx) \cdot \nabla u + Mu \\ \operatorname{div} u &= 0 && \text{in } \Omega, t > 0 \\ u(x, t) &= Mx - U && \text{on } \partial\Omega, t > 0 \\ u(x, t) &\rightarrow 0 && \text{for } |x| \rightarrow \infty \end{aligned}$$

u : velocity, π : pressure, " $U = u(\infty)$ ",

Ω exterior domain, e^{Mt} : rotation matrix, i.e. $Mx = \omega \times x$

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Set

$$b(x) = \frac{1}{2} \operatorname{rot} [\eta(x) (U \times x - |x|^2 \omega)]$$

Homogeneous boundary data

Then $(u - b, p)$ satisfies

$$\begin{aligned} u_t - \Delta u + \nabla \pi + (U - Mx) \cdot \nabla u + Mu &= \operatorname{div}(F - Q_b(u)) && \text{in } \Omega, t > 0 \\ \operatorname{div} u &= 0 && \text{in } \Omega, t > 0 \\ u(x, t) &= 0 && \text{on } \partial\Omega, t > 0 \\ u(x, t) &\rightarrow 0 && \text{for } |x| \rightarrow \infty \end{aligned}$$

with

$$Q_b(u) = (u + b) \otimes (u + b) - \nabla b + (U - Mx) \otimes b + b \otimes (Mx)$$

Homogeneous boundary data



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Then $(u - b, p)$ satisfies

We consider stationary solutions here:

$$\begin{aligned} \textcolor{blue}{u_t} - \Delta u + \nabla \pi + (U - Mx) \cdot \nabla u + Mu &= \operatorname{div}(F - Q_b(u)) && \text{in } \Omega \\ \operatorname{div} u &= 0 && \text{in } \Omega \\ u(x \rightarrow \infty) &= 0 && \text{on } \partial\Omega \\ u(x \rightarrow \infty) &\rightarrow 0 && \text{for } |x| \rightarrow \infty \end{aligned}$$

with

$$Q_b(u) = (u + b) \otimes (u + b) - \nabla b + (U - Mx) \otimes b + b \otimes (Mx)$$

Known results

- ▶ Galdi: Weak and strong solutions, $U = 0$,
pointwise estimates under decay assumption on the force.
- ▶ Silvestre: Strong solutions, $U \neq 0$
- ▶ Galdi/Silvestre: Decay estimates of strong solutions, $U \neq 0$
- ▶ Farwig/Hishida/Müller: L^p -theory for a model problem with $U = 0$ in \mathbb{R}^n
- ▶ Hishida: L^p -setting for weak solutions, $U = 0$, $\Omega = \mathbb{R}^3$ or exterior
- ▶ Farwig: Strong solutions in L^p , $U \neq 0$
- ▶ Farwig/Hishida: Weak solutions in Lorentz spaces, $U = 0$
- ▶ Hishida/Shibata: Stability of stationary solutions in weak L^3
- ▶ Necasova/Kracmar/Penel: Weak solutions, L^p -setting, $U \neq 0$

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Comments on the proof

The critical space $L^3(\Omega)$, is too restrictive.

One possible way is to switch to the class $L_{3,\infty}(\Omega)$.

Definition

$$\theta \in (0, 1), 1 < r < s < \infty, q \in [1, \infty], \frac{1}{p} = \frac{(1-\theta)}{r} + \frac{\theta}{s}$$

- ▶ Lorentz spaces: $L_{p,q}(\Omega) := (L^r(\Omega), L^s(\Omega))_{\theta,q}$
- ▶ Homogeneous Sobolev-Lorentz spaces: $\dot{H}_{p,q}^1(\Omega) := (\dot{H}_r^1(\Omega), \dot{H}_s^1(\Omega))_{\theta,q}$
Note: $C_0^\infty(\Omega)$ is not dense in $\dot{H}_{p,\infty}^1(\Omega)$, set $\widehat{H}_{p,q}^1(\Omega) := \overline{C_0^\infty(\Omega)}$
- ▶ negative spaces: $\dot{H}_{p,q}^{-1}(\Omega) := (\widehat{H}_{p',q'}^1(\Omega))^*$

Remark

- ▶ Sobolev imbedding and real interpolation gives $\dot{H}_{3/2,\infty}^1(\Omega) \subset L_{3,\infty}(\Omega)$
- ▶ For $[u] \in \dot{H}_{n,1}^1(\Omega)$ there exists a representative $u \in BC(\Omega)$ with $u(x) \rightarrow 0$ as $|x| \rightarrow \infty$

Definition

We say that $(u, \pi) \in \dot{H}_{p,q}^1(\Omega) \times L_{p,q}(\Omega)$, $\operatorname{div} u = 0$, is a weak solution if $(\omega \times x - U) \cdot \nabla u - \omega \times u \in \dot{H}_{p,q}^{-1}(\Omega)$ and

$$\langle \nabla u, \nabla \varphi \rangle - \langle (\omega \times x - U) \cdot \nabla u - \omega \times u, \varphi \rangle - \langle Q_b(u), \nabla \varphi \rangle - \langle \pi, \operatorname{div} \varphi \rangle = \langle F, \nabla \varphi \rangle$$

for all $\varphi \in C_0^\infty(\Omega)$

Theorem (H., Kim, Kozono)

$$V_{p,q} := \dot{H}_{3/2,\infty}^1(\Omega) \cap \dot{H}_{p,q}^1(\Omega), \quad \Pi_{p,q} := L_{\frac{3}{2},\infty}(\Omega) \cap L_{p,q}(\Omega)$$

Let $(p, q) = (\frac{3}{2}, \infty)$ or $(p, q) \in (\frac{3}{2}, 3) \times [1, \infty]$.

1. $F \in \Pi_{p,q}$ with $|U| + |\omega| + \|F\|_{3/2,\infty}$ small enough

⇒ Existence of $(u, \pi) \in V_{p,q} \times \Pi_{p,q}$ with

$$\|u\|_{3,\infty} + \|\nabla u\|_{3/2,\infty} + \|\pi\|_{3/2,\infty} \leq C(|U| + |\omega| + \|F\|_{3/2,\infty})$$

$$\|u\|_{p^*,q} + \|\nabla u\|_{p,q} + \|\pi\|_{p,q} \leq C(|U| + |\omega| + \|F\|_{p,q})$$

(here: $p^* = 3p/(3-p)$)

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2. If $(p, q) \in (\frac{3}{2}, 3) \times [1, \infty]$ the solution is unique
3. If $(p, q) = (\frac{3}{2}, \infty)$ there exists η such that

$$\|u\|_{3,\infty} \leq \eta \quad \Rightarrow \quad \text{Uniqueness}$$

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The linear problem

Set $Lu = -\Delta u + (U - \omega \times x) \cdot \nabla u + \omega \times u$, and consider

$$\begin{aligned} Lu + \nabla \pi &= f && \text{in } \Omega \\ \operatorname{div} u &= g && \text{in } \Omega \\ u &= 0 && \text{on } \partial\Omega \end{aligned} \tag{1}$$

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Proposition

(i) $p = \frac{3}{2}$, $q = \infty$ or (ii) $\frac{3}{2} < p < 3$, $1 \leq q \leq \infty$ or (iii) $p = 3$, $q = 1$.

$f \in \dot{H}_{p,q}^{-1}(\Omega)$ and $g \in L_{p,q}(\Omega)$ with $(U - \omega \times x)g \in \dot{H}_{p,q}^{-1}(\Omega)$,

then there exists a unique weak solution $(u, \pi) \in \dot{H}_{p,q}^1(\Omega) \times L_{p,q}(\Omega)$ of (1).

Moreover, for $|U| + |\omega| \leq M < \infty$

$$\|u\|_{p^*,q} + \|\nabla u\|_{p,q} + \|\pi\|_{p,q} \leq C (\|f\|_{-1,p,q} + \|g\|_{p,q} + \|(U - \omega \times x)g\|_{-1,p,q}). \tag{2}$$

Proof of the proposition

- ▶ Existence is proved by localization using corresponding results in \mathbb{R}^3 and bounded domains.
- ▶ The uniqueness follows from

Lemma

Let (p_i, q_i) , $i = 1, 2$ satisfy (i), (ii) or (iii). Let $s > 3/2$.

$f = \operatorname{div} F \in L_2(\Omega)$ with $(1 + |x|^2) F \in L_\infty(\Omega)$.

Then a weak solution $u \in \dot{H}_{p_1, q_1}^1(\Omega) + \dot{H}_{p_2, q_2}^1(\Omega)$, $\pi \in L_{p_1, q_1}(\Omega) + L_{p_2, q_2}(\Omega)$ satisfies

$$u \in \dot{H}_2^1(\Omega),$$

$$(1 + |x|) u \in L_\infty(\Omega),$$

$$\nabla^2 u \in L_2(\Omega),$$

$$\pi \in H_2^1(\Omega) \cap L_s(\Omega)$$

and

$$\int_{\Omega} |\nabla u|^2 dx = - \int_{\Omega} F \cdot \nabla u dx. \quad (3)$$

It thus follows that if $f \equiv 0$, then $(u, \pi) = (0, 0)$ in Ω .

The nonlinear problem: proof of the main result



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Existence: For $u \in V_{p,q}$ define $v = T(u)$ where

$$\begin{aligned} Lv + \nabla \pi &= \operatorname{div}(F - Q_b(u)) \quad \text{in } \Omega \\ \operatorname{div} v &= 0 \quad \text{in } \Omega \\ v &= 0 \quad \text{on } \partial\Omega \end{aligned}$$

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Estimates for the linear problem yields

$$\|\nabla T(u)\|_{3/2,\infty} \leq 2C(|U| + |\omega| + \|F\|_{3/2,\infty})$$

$$\|\nabla T(u)\|_{V_{p,q}} \leq 2C(|U| + |\omega| + \|F\|_{p,q})$$

$$\|T(u_1) - T(u_2)\|_{V_{p,q}} \leq C(\|\nabla u_1\|_{3/2,\infty} + \|\nabla u_2\|_{3/2,\infty}) \|u_1 - u_2\|_{V_{p,q}}$$

provided $\|\nabla u\|_{3/2,\infty} \leq 2C(|U| + |\omega| + \|F\|_{3/2,\infty})$

and $\|\nabla u\|_{p,q} \leq 2C(|U| + |\omega| + \|F\|_{p,q}).$

Then use contraction mapping principle

Proof of the main result

Uniqueness:

Let $(u_1, \pi_1), (u_2, \pi_2)$ be two solutions. Then for $(u, \pi) := (u_1 - u_2, \pi_1 - \pi_2)$

$$Lu + \nabla \pi = \operatorname{div} G$$

where $G = Q_b(u_2) - Q_b(u_1) = u \otimes (u_1 + b) + (u_2 + b) \otimes v$.

A bootstrap argument with $V_{p,q} \subset V_{p,\infty} \subset L_{3,\infty}(\Omega) \cap L_{p^*,\infty}(\Omega)$ let us find

$$(u, \pi) \in \dot{H}_2^1(\Omega) \times L_2(\Omega)$$

Estimating G finally yields

$$\|\nabla u\|_2^2 \leq C_0 (|U| + |\omega| + \|F\|_{3/2,\infty}) \|\nabla u\|_2^2$$

$$\rightsquigarrow \|\nabla u\|_2^2 = 0. \quad (\text{if } |U| + |\omega| + \|F\|_{3/2,\infty} \text{ is small})$$