



Non-autonomous Ornstein-Uhlenbeck type operators in exterior domains

Joint work with A. Rhandi (Salerno)

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Motivation:

The Navier-Stokes flow in the exterior of a rotating obstacle



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Setup:

- ▶ $K \subset \mathbb{R}^3$ a **compact obstacle**
- ▶ the **exterior of the obstacle** $\Omega := \mathbb{R}^3 \setminus K$ filled with a viscous incompressible fluid
- ▶ K is **rotating** with **prescribed time-dependent angular velocity**:

$$m \in C([0, \infty); \mathbb{R}^{3 \times 3}) \quad \text{with} \quad m(t)^T = -m(t) \quad \text{for all} \quad t \geq 0$$

- ▶ **exterior of the rotated obstacle at time t** : $\Omega(t) := Q(t)\Omega$, where $Q(t)$ solves

$$\begin{cases} \partial_t Q(t) &= m(t)Q(t), \quad t > 0, \\ Q(0) &= \text{Id.} \end{cases}$$

- ▶ fluid flow subject to an **outflow condition**: fluid has a **prescribed velocity** $v_\infty \in \mathbb{R}^3$ far away from the obstacle

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The equations for the fluid: **Navier-Stokes Equations**

$$\left\{ \begin{array}{ll} v_t - \Delta v + v \cdot \nabla v + \nabla q &= 0 & \text{in } \mathbb{R}_+ \times \Omega(t), \\ \operatorname{div} v &= 0 & \text{in } \mathbb{R}_+ \times \Omega(t), \\ v(t, y) &= m(t)y & \text{in } \mathbb{R}_+ \times \partial\Omega(t), \\ \lim_{|y| \rightarrow \infty} v(t, y) &= v_\infty \neq 0 & \text{for } t \in \mathbb{R}_+, \\ v(0, y) &= v_0(y) & \text{in } \Omega. \end{array} \right.$$

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Transformation: $x = Q(t)^T y$, $u(t, x) = Q(t)^T (v(t, y) - v_\infty)$, $p(t, x) = q(t, y)$

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$$\left\{ \begin{array}{ll} u_t - \Delta u - (M(t)x) \cdot \nabla u + M(t)u \\ \quad + (Q(t)^T v_\infty) \cdot \nabla u + u \cdot \nabla u + \nabla p &= 0 & \text{in } \mathbb{R}_+ \times \Omega, \\ \operatorname{div} u &= 0 & \text{in } \mathbb{R}_+ \times \Omega, \\ u(t, x) &= M(t)x - Q(t)^T v_\infty & \text{in } \mathbb{R}_+ \times \partial\Omega, \\ \lim_{|x| \rightarrow \infty} u(t, x) &= 0 & \text{for } t \in \mathbb{R}_+, \\ u(0, x) &= v_0(x) & \text{in } \Omega, \end{array} \right.$$

where $M(t) := Q(t)^T m(t) Q(t)$.

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Linearization leads to operators of the form

$$A(t)u(x) := \mathbb{P} \left(\Delta u + (M(t)x - Q(t)^T v_\infty) \cdot \nabla u - M(t)u \right), \quad t > 0, x \in \Omega.$$

Some known results:

- ▶ **Autonomous case** $M(t) \equiv M$ and $v_\infty = 0$
 - ▶ Hishida '99 (L^2 -theory)
 - ▶ Geissert, Heck, Hieber '06 (L^p -theory)
 - ▶ Hishida, Shibata '09
- ▶ **Autonomous case** $M(t) \equiv M$ and $Mv_\infty = 0$
 - ▶ Shibata '08
- ▶ **Non-autonomous case**
 - ▶ Hishida '01 (L^2 -theory and $M(t) = (0, 0, \omega_0(t)) \times$)



Consider **Ornstein-Uhlenbeck type operators** (for functions $\varphi : \mathbb{R}^d \rightarrow \mathbb{R}$)

$$\mathcal{L}_\Omega(t)\varphi(x) = \Delta\varphi(x) + \langle M(t)x + c(t), \nabla\varphi(x) \rangle, \quad x \in \Omega, \quad t > 0,$$

The parabolic problem with Dirichlet boundary conditions

$$\begin{cases} u_t(t, x) - \mathcal{L}_\Omega(t)u(t, x) &= 0, & t \in (s, \infty), x \in \Omega, \\ u(t, x) &= 0, & t \in (s, \infty), x \in \partial\Omega, \\ u(s, x) &= f(x), & x \in \Omega. \end{cases}$$

Interesting case: $\Omega \subset \mathbb{R}^d$ is an **exterior domain**, i.e. $\Omega := \mathbb{R}^d \setminus K$ and $\partial\Omega$ smooth

Assumptions:

- ▶ $M \in C_{loc}^\alpha(\mathbb{R}_+, \mathbb{R}^{d \times d})$, $c \in C_{loc}^\alpha(\mathbb{R}_+, \mathbb{R}^d)$ for some $\alpha \in (0, 1)$

Non-autonomous abstract Cauchy problem



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Set

$$\mathcal{D}(L_\Omega(t)) := \{u \in W^{2,p}(\Omega) \cap W_0^{1,p}(\Omega) : \langle M(t)x, \nabla u(x) \rangle \in L^p(\Omega)\},$$

$$L_\Omega(t)u := \mathcal{L}_\Omega(t)u.$$

Non-autonomous abstract Cauchy Problem:

$$(CP) \quad u'(t) = L_\Omega(t)u(t), \quad 0 \leq s < t, \quad u(s) = f \in L^p(\Omega),$$

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Non-autonomous abstract Cauchy Problem:

$$(CP) \quad u'(t) = L_{\Omega}(t)u(t), \quad 0 \leq s < t, \quad u(s) = f \in L^p(\Omega),$$

Definition. $T_{\Omega}(\cdot, \cdot) \in \mathcal{L}(L^p(\Omega))$ is an evolution system if

- ▶ $T_{\Omega}(s, s) = \text{Id}$, and $T_{\Omega}(t, s) = T_{\Omega}(t, r)T_{\Omega}(r, s)$,
- ▶ $(t, s) \mapsto T_{\Omega}(t, s)$ is strongly continuous, for $0 \leq s \leq r \leq t$.

(CP) **well-posed** if there exists an evolution system $T_{\Omega}(\cdot, \cdot)$ and dense subspaces Y_s of $L^p(\Omega)$ such that $T_{\Omega}(t, s)Y_s \subset Y_t \subset \mathcal{D}(L_{\Omega}(t))$ for $0 \leq s \leq t$ and the function $u(t) := T_{\Omega}(t, s)f$ is a solution of (CP) for $f \in Y_s$. We say $L_{\Omega}(\cdot)$ generates $T_{\Omega}(\cdot, \cdot)$.

Non-autonomous abstract Cauchy problem



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Well known: For fixed t , $(L_\Omega(t), \mathcal{D}(L_\Omega(t)))$ generates C_0 -semigroup (**not analytic !**)

Classical generation results for non-autonomous problems:

- ▶ Parabolic evolution systems
 \rightsquigarrow generators of analytic semigroups
- ▶ Hyperbolic evolution systems
 \rightsquigarrow stable family of generators

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Strategy:

- ▶ Study the whole space \mathbb{R}^d
 \rightsquigarrow use representation formula (Da Prato/Lunardi '07, Geissert/Lunardi '08)
- ▶ Study bounded domains D
 \rightsquigarrow apply standard results for parabolic problems
- ▶ Use some cut-off technique for exterior domain



Lemma

Let $U(\cdot, \cdot)$ be the evolution system in \mathbb{R}^d that satisfies $\partial_t U(t, s) = -M(t)U(t, s)$.

For $t > s$ set

$$T_{\mathbb{R}^d}(t, s)f(x) = \frac{1}{(4\pi)^{\frac{d}{2}}(\det Q_{t,s})^{\frac{1}{2}}} \int_{\mathbb{R}^d} f(U(s, t)x + g(t, s) - y) e^{-\frac{1}{4}\langle Q_{t,s}^{-1}y, y \rangle} dy,$$

$$\text{where } g(t, s) = \int_s^t U(s, r)c(r)dr \quad \text{and} \quad Q_{t,s} = \int_s^t U(s, r)U^*(s, r)dr.$$



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- ▶ $L_{\mathbb{R}^d}(\cdot)$ generates $T_{\mathbb{R}^d}(\cdot, \cdot)$.
- ▶ Let $T > 0$, $1 < p \leq q < \infty$ and $\beta \in \mathbb{N}_0^d$. There exists $C := C(T) > 0$ s.t.
 - ▶ $\|T_{\mathbb{R}^d}(t, s)f\|_q \leq C(t-s)^{-\frac{d}{2}(\frac{1}{p}-\frac{1}{q})} \|f\|_p, \quad 0 \leq s < t < T,$
 - ▶ $\|\partial_x^\beta T_{\mathbb{R}^d}(t, s)f\|_p \leq C(t-s)^{-\frac{|\beta|}{2}} \|f\|_p, \quad 0 \leq s < t < T.$



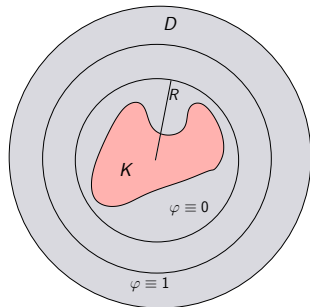
Lemma

Let $D \subset \mathbb{R}^d$ be a bounded domain with $C^{1,1}$ -boundary.

- ▶ $L_D(\cdot)$ generates an evolution system $T_D(\cdot, \cdot)$.
- ▶ Let $T > 0$, $1 < p < \infty$ and $p \leq q < \infty$. There exists $C := C(T) > 0$ s.t.
 - ▶ $\|T_D(t, s)f\|_q \leq C(t-s)^{-\frac{d}{2}(\frac{1}{p}-\frac{1}{q})} \|f\|_p, \quad 0 \leq s < t < T,$
 - ▶ $\|\nabla T_D(t, s)f\|_p \leq C(t-s)^{-\frac{1}{2}} \|f\|_p, \quad 0 \leq s < t < T,$
 - ▶ $\|\nabla^2 T_D(t, s)f\|_p \leq C(t-s)^{-1} \|f\|_p, \quad 0 \leq s < t < T.$

- ▶ Consider exterior domain $\Omega = \mathbb{R}^d \setminus K$.
- ▶ Let $R > 0$ s.t. $K \subset B(R)$.
- ▶ Set $D := \Omega \cap B(R+3)$.
- ▶ Consider a cut-off fct. $\varphi \in C^\infty(\Omega)$ s.t.
 $0 \leq \varphi \leq 1$ and

$$\varphi(x) := \begin{cases} 1, & |x| \geq R+2, \\ 0, & |x| \leq R+1, \end{cases}$$



- ▶ For $f \in L^p(\Omega)$ set $W(t,s)f = \varphi T_{\mathbb{R}^d}(t,s)f_0 + (1-\varphi)T_D(t,s)f_D$.



Short calculation: $W(t, s)f$ solves inhomogeneous problem

$$\begin{cases} \partial_t W(t, s)f &= L_\Omega(t)W(t, s)f - F(t, s)f, & 0 \leq s < t, \\ W(s, s)f &= f, \end{cases}$$

with error terms

$$\begin{aligned} F(t, s)f &= 2\nabla\varphi(\nabla T_{\mathbb{R}^d}(t, s)f_0 + \nabla T_D(t, s)f_D) \\ &\quad + (\Delta\varphi + (M(t)x + c(t))\nabla\varphi)(T_{\mathbb{R}^d}(t, s)f_0 + T_D(t, s)f_D). \end{aligned}$$

Estimate for error terms:

$$\|F(t, s)f\|_p \leq C(t-s)^{-\frac{1}{2}}\|f\|_p, \quad 0 \leq s < t < T,$$

for every $T > 0$.



Consider the integral equation ([Variation of constant formula](#))

$$T_{\Omega}(t, s)f = W(t, s)f + \int_s^t T_{\Omega}(t, r)F(r, s)f \, dr, \quad t \geq s \geq 0, f \in L^p(\Omega).$$

Solution to integral equation:

$$T_{\Omega}(t, s)f = \sum_{k=0}^{\infty} T_k(t, s)f$$

where $T_0(t, s)f = W(t, s)f$ and

$$T_{k+1}(t, s)f = \int_s^t T_k(t, r)F(r, s)f \, dr.$$

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$$T_{k+1}(t, s)f = \int_s^t T_k(t, r)F(r, s)f \, dr.$$

(Technical) calculation yields:

$$\partial_t T_{\Omega}(t, s)f = L_{\Omega}(t)T_{\Omega}(t, s)f \quad \text{and} \quad \partial_s T_{\Omega}(t, s)f = -T_{\Omega}(t, s)L_{\Omega}(s)f$$

for "nice" functions f .

Result:

Well-posedness and L^p -estimates in exterior domains



Theorem

Let $\Omega \subset \mathbb{R}^d$ be an exterior domain with $C^{1,1}$ -boundary and $1 < p < \infty$.

- ▶ $L_\Omega(\cdot)$ generates $T_\Omega(\cdot, \cdot)$.
- ▶ Let $T > 0$, $1 < p < \infty$ and $p \leq q < \infty$. There exists $C := C(T) > 0$ s.t.
 - ▶ $\|T_\Omega(t, s)f\|_{L^q(\Omega)} \leq C(t-s)^{-\frac{d}{2}(\frac{1}{p}-\frac{1}{q})} \|f\|_{L^p(\Omega)}, \quad 0 \leq s < t < T,$
 - ▶ $\|\nabla T_\Omega(t, s)f\|_{L^p(\Omega)} \leq C(t-s)^{-\frac{1}{2}} \|f\|_{L^p(\Omega)} \quad 0 \leq s < t < T,$
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