

# Qualitative Behavior of Solutions for the Two-Phase Navier-Stokes Equations with Surface Tension

Mathias Wilke

Joint work with M. Köhne & J. Prüss

Martin-Luther University Halle-Wittenberg  
Faculty of Natural Sciences III  
Institute for Mathematics

Waseda University, Tokyo, March 8-16, 2010

$\Omega \subset \mathbb{R}^n$  open bounded domain with smooth boundary,  $\Omega_i(t)$  subdomains occupied by immiscible incompressible fluid  $i = 1, 2$ ,  $\Gamma(t)$  interface separating the two phases. No boundary contact, i.e.  $\Gamma(t) \cap \partial\Omega = \emptyset$ , no phase transitions, isothermal conditions and no external forces.

$u = u(t, x)$  velocity field,  $\pi = \pi(t, x)$  pressure field

$S(t, x)$  stress tensor

$E(t, x) := \frac{1}{2}(\nabla u(t, x) + \nabla u(t, x)^T)$  rate of strain tensor

$\rho_i > 0$  densities,  $\mu_i > 0$  viscosities in the phases

$\nu_\Gamma(t, x)$  the normal at  $x \in \Gamma(t)$  directed into  $\Omega_2(t)$

$V_\Gamma(t, x) = (u(t, x)|\nu_\Gamma(t, x))$  normal velocity of  $\Gamma(t)$

$H_\Gamma(t, x) = -\operatorname{div}_\Gamma \nu_\Gamma(t, x)$  curvature of  $\Gamma(t)$

$$[[\phi]] = \lim_{h \rightarrow 0^+} [\phi(t, x + h\nu_\Gamma(t, x)) - \phi(t, x - h\nu_\Gamma(t, x))]$$

is the jump of the quantity  $\phi$  across  $\Gamma(t)$ .

# The Two-Phase Navier-Stokes Problem

In the bulk phases:

$$\begin{aligned}\partial_t(\rho u) + \nabla \cdot (\rho u \otimes u - S) &= 0, & x \in \Omega \setminus \Gamma(t), \quad t > 0, \\ \nabla \cdot u &= 0, & x \in \Omega \setminus \Gamma(t), \quad t > 0, \\ \mu(\nabla u + \nabla u^T) - \pi I &= S, & x \in \Omega \setminus \Gamma(t), \quad t > 0.\end{aligned}$$

At the interface:

$$\begin{aligned}[[u]] &= 0, & x \in \Gamma(t), \quad t > 0, \\ (u|_{\nu_\Gamma}) &= V_\Gamma, & x \in \Gamma(t), \quad t > 0, \\ -[[S]] \nu_\Gamma &= \sigma H_\Gamma \nu_\Gamma, & x \in \Gamma(t), \quad t > 0.\end{aligned}$$

Initial conditions:

$$u(0, x) = u_0(x) \quad x \in \Omega, \quad \Gamma(0) = \Gamma_0.$$

No-slip boundary conditions at  $\partial\Omega$ , i.e.  $u = 0$  on  $\partial\Omega$ .

*One-phase problems with surface tension:*

BEALE 1980, 1984, SOLONNIKOV 1987-, TANI & TANNAKA 1996, SHIMIZU & SHIBATA 2005-.

*Two phase problems with surface tension:*

DENISOVA 1988-, TANI 1996, TANNAKA 1995, SHIMIZU & SHIBATA 2009, PRÜSS & SIMONETT 2009.

Of particular relevance for convergence of solutions are the papers of BEALE and SOLONNIKOV, both in the *one-phase case*.

Here we are interested in the **qualitative and asymptotic behaviour** of solutions of the two-phase problem.

## Theorem

Fix  $p > n + 2$ , let  $\partial\Omega \in C^3$ , and suppose

$$\Gamma_0 \in W_p^{3-2/p}, \quad u_0 \in W_p^{2-2/p}(\Omega \setminus \Gamma_0)^n.$$

Assume the compatibility conditions

$$\begin{aligned} \operatorname{div} u_0 &= 0 \text{ in } \Omega \setminus \Gamma_0, \quad u = 0 \text{ on } \partial\Omega, \\ \llbracket \mathcal{P}_{\Gamma_0} \mu E_0 \nu_{\Gamma_0} \rrbracket &= 0, \quad \llbracket u_0 \rrbracket = 0 \text{ on } \Gamma_0, \end{aligned}$$

where  $E_0 = \frac{1}{2}(\nabla u_0 + \nabla u_0^T)$ , and  $\mathcal{P}_{\Gamma_0} = I - \nu_{\Gamma_0} \times \nu_{\Gamma_0}$ .

## Theorem

Then there exists  $t_0 = t_0(u_0, \Gamma_0) > 0$  and a unique classical solution  $(u, \pi, \Gamma)$  of the problem on  $(0, t_0)$ . The set

$$\bigcup_{t \in (0, t_0)} \{t\} \times \Gamma(t)$$

is a real analytic manifold, and with

$$\mathcal{U} := \{(t, x) \in (0, t_0) \times \Omega, x \notin \Gamma(t)\},$$

the function  $(u, \pi) : \mathcal{U} \rightarrow \mathbb{R}^{n+1}$  is real analytic.

# Strategy for the proof

Approximate  $\Gamma_0$  by a smooth hypersurface  $\Sigma$ .

## a) Transformation to a Fixed Domain (Hanzawa)

Let  $d(x)$  denote the signed distance of  $x \in \mathbb{R}^n$  to  $\Sigma$ , and  $\Pi(x)$  the projection of  $x \in \mathbb{R}^n$  to  $\Sigma$ . Then

$$\Lambda : \Sigma \times (-a, a) \rightarrow \mathbb{R}^n$$

$$\Lambda(p, r) := p + r\nu_\Sigma(p), \quad \Lambda^{-1}(x) = (\Pi(x), d(x))$$

is a diffeomorphism from  $\Sigma \times (-a, a)$  onto

$\mathcal{R}(\Lambda) = \{x \in \mathbb{R}^n : |d(x)| < a\}$ , provided

$$0 < a < \min\{r, 1/\kappa_j(x) : j = 1, \dots, n-1, x \in \Sigma\},$$

where  $\kappa_j(x)$  mean the principal curvatures of  $\Sigma$  at  $x \in \Sigma$  and

$$\bar{B}_r(p \pm r\nu_\Sigma(p)) \cap \Sigma = \{p\}, \quad p \in \Sigma.$$

Use this to parameterize  $\Gamma(t)$  over  $\Sigma$ :

$$\Gamma(t) : p \mapsto p + h(t, p)\nu_\Sigma(p), \quad p \in \Sigma, t \geq 0.$$

Extend this diffeomorphism to all of  $\Omega$ :

$$\Theta(t, x) = x + \chi(d(x))h(t, \Pi(x))\nu_\Sigma(\Pi(x)).$$

Here  $\chi$  denotes a suitable cut-off function. This way  $\Omega \setminus \Gamma(t)$  is transformed to the fixed domain  $\Omega \setminus \Sigma$ . Set

$$\begin{aligned}\bar{u}(t, x) &= u(t, \Theta(t, x)), \\ \bar{\pi}(t, x) &= \pi(t, \Theta(t, x)), \quad t > 0, x \in \Omega \setminus \Sigma.\end{aligned}$$

This yields the problem (drop the bars!)

$$\begin{aligned}\rho \partial_t u - \mu \mathcal{A}(h)u + \mathcal{G}(h)\pi &= \mathcal{R}(u, h) \quad \text{in } \Omega \setminus \Sigma, \\ (\mathcal{G}(h)|u) &= 0 \quad \text{in } \Omega \setminus \Sigma, \\ u &= 0 \quad \text{on } \partial\Omega, \\ \llbracket -\mu(\mathcal{G}(h)u + [\mathcal{G}(h)u]^\top) + \pi \rrbracket \nu_\Gamma(h) &= \sigma H_\Gamma(h)\nu_\Gamma(h) \quad \text{on } \Sigma, \\ \llbracket u \rrbracket &= 0 \quad \text{on } \Sigma, \\ \partial_t h - (u|\nu_\Sigma) &= -(u|\alpha(h)), \quad \text{on } \Sigma, \\ u(0) &= u_0, \quad h(0) = h_0.\end{aligned} \tag{1}$$



Here  $\mathcal{A}(h)$  and  $\mathcal{G}(h)$  denote the transformed Laplacian, resp. gradient. With the curvature tensor  $L_\Sigma$  and the surface gradient  $\nabla_\Sigma$  we have

$$\begin{aligned} \nu_\Gamma(h) &= \beta(h)(\nu_\Sigma - \alpha(h)), & \alpha(h) &= M(h)\nabla_\Sigma h, \\ M(h) &= (I - hL_\Sigma)^{-1}, & \beta(h) &= (1 + |\alpha(h)|^2)^{-1/2}, \end{aligned}$$

and

$$V = (\partial_t \Theta|_{\nu_\Gamma}) = \partial_t h(\nu_\Gamma|_{\nu_\Sigma}) = \beta(h)\partial_t h.$$

The curvature  $H_\Gamma(h)$  becomes

$$\begin{aligned} H_\Gamma(h) &= \beta(h)\{\text{tr}[M(h)(L_\Sigma + \nabla_\Sigma \alpha(h))] \\ &\quad - \beta^2(h)(M(h)\alpha(h)|[\nabla_\Sigma \alpha(h)]\alpha(h))\}, \end{aligned}$$

a differential expression involving second order derivatives of  $h$  only linearly. Linearization of  $H_\Gamma(h)$  at  $h = 0$ :  $H'_\Gamma(0) = \text{tr} L_\Sigma^2 + \Delta_\Sigma$ , where  $\Delta_\Sigma$  denotes the Laplace-Beltrami operator on  $\Sigma$ .

Rewrite this problem in quasilinear form.

$$\begin{aligned} \rho \partial_t u - \mu \Delta u + \nabla \pi &= F(u, \pi, h) \quad \text{in } \Omega \setminus \Sigma, \\ \operatorname{div} u &= F_d(u, h) \quad \text{in } \Omega \setminus \Sigma, \\ u &= 0 \quad \text{on } \partial\Omega, \\ \llbracket -\mu(\nabla u + \nabla u^\top) + \pi \rrbracket \nu_\Sigma - \sigma(\Delta_\Sigma h) \nu_\Sigma &= G(u, \llbracket \pi \rrbracket, h) \quad \text{on } \Sigma, \\ \llbracket u \rrbracket &= 0 \quad \text{on } \Sigma, \\ \partial_t h - (u|_{\nu_\Sigma}) &= G_h(u, h) \quad \text{on } \Sigma, \\ u(0) &= u_0, \quad h(0) = h_0 \end{aligned} \tag{2}$$

The right hand sides in this problem consist of lower order terms and of terms of the same order appearing on the left, but carrying a factor  $|\nabla_\Sigma h|$ , which is small by construction.

## b) The Linear Problem

Establish maximal  $L_p$ -regularity for the linear problem defined by the l.h.s. of (2). In particular, find the right spaces for the data, such that the *solution-to-data map* for the following inhomogeneous linear problem becomes an *isomorphism*.

$$\begin{aligned} \rho \partial_t v - \mu \Delta v + \nabla q &= f_v \quad \text{in } \Omega \setminus \Sigma, \\ \operatorname{div} v &= f_d \quad \text{in } \Omega \setminus \Sigma \\ v &= 0 \quad \text{on } \partial\Omega, \\ \llbracket -\mu(\nabla v + \nabla v^T) + q \rrbracket \nu_\Sigma - \sigma(\Delta_\Sigma h) \nu_\Sigma &= g \quad \text{on } \Sigma, \quad (3) \\ \llbracket v \rrbracket &= 0 \quad \text{on } \Sigma, \\ \partial_t h - (v|_{\nu_\Sigma}) &= g_h \quad \text{on } \Sigma, \\ v(0) &= v_0, \quad h(0) = h_0. \end{aligned}$$

This is proved by localization and perturbation, and a corresponding result for a flat interface, i.e.  $\Omega = \mathbb{R}^n$ ,  $\Sigma = \mathbb{R}^{n-1} \times \{0\}$ ; see PRÜSS & SIMONETT 2009.

The solutions of the transformed problem will belong to the following class:

$$v \in H_p^1(J; L_p(\Omega)^n) \cap L_p(J; H_p^2(\Omega \setminus \Sigma)^n), \quad q \in L_p(J; \dot{H}_p^1(\Omega \setminus \Sigma)),$$

$$[[q]] \in W_p^{1/2-1/2p}(J; L_p(\Sigma)) \cap L_p(J; W_p^{1-1/p}(\Sigma)),$$

$$h \in W_p^{2-1/2p}(J; L_p(\Sigma)) \cap H_p^1(J; W_p^{2-1/p}(\Sigma)) \cap L_p(J; W_p^{3-1/p}(\Sigma)),$$

provided

$$v_0 \in W_p^{2-2/p}(\Omega \setminus \Sigma)^n, \quad h_0 \in W_p^{3-2/p}(\Sigma),$$

and the natural compatibility conditions hold.

# The Linear Problem - Main Result

## Theorem

Let  $1 < p < \infty$ ,  $\rho_j, \mu_j, \sigma$  be positive constants,  $j = 1, 2$ ; set  $J = [0, a]$ . Then the two-phase Stokes problem (3) admits a unique solution  $(v, q, h)$  with regularity

$$v \in H^1(J; L_p(\Omega))^n \cap L_p(J; H_p^2(\Omega \setminus \Sigma))^n, \quad q \in L_p(J; \dot{H}_p^1(\Omega \setminus \Sigma)),$$

$$[[q]] \in W_p^{1/2-1/2p}(J; L_p(\Sigma)) \cap L_p(J; W_p^{1-1/p}(\Sigma)),$$

$$h \in W_p^{2-1/2p}(J; L_p(\Sigma)) \cap H_p^1(J; W_p^{2-1/p}(\Sigma)) \cap L_p(J; W_p^{3-1/p}(\Sigma)).$$

if and only if the data  $(v_0, h_0, f, f_d, g, g_h)$  satisfy the following regularity and compatibility conditions.

## Theorem

- (a)  $f_v \in L_p(J \times \Omega)^n$ ,  $v_0 \in W_p^{2-2/p}(\Omega \setminus \Sigma)^n$ ,  $v_0 = 0$  on  $\partial\Omega$ ;
- (b)  $f_d \in H_p^1(J; H_p^{-1}(\Omega \setminus \Sigma)) \cap L_p(J; H_p^1(\Omega \setminus \Sigma))$ ,  $\operatorname{div} v_0 = f_d(0)$ ;
- (c)  $g \in W_p^{1/2-1/2p}(J; L_p(\Sigma)) \cap L_p(J; W_p^{1-1/p}(\Sigma))$ ;
- (d)  $[[v_0]] = 0$ ,  $\mathcal{P}_\Sigma[[\mu(\nabla v_0 + \nabla v_0^T)]] = g_v(0)$ ;
- (e)  $h_0 \in W_p^{3-2/p}(\Sigma)$ ;
- (f)  $g_h \in W_p^{1-1/2p}(J; L_p(\Sigma)) \cap L_p(J; W_p^{2-1/p}(\Sigma))$ .

The solution map  $(v_0, h_0, f, f_d, g, g_h) \mapsto (v, q, h)$  is continuous between the corresponding spaces.

### c) The Nonlinear Problem

Based on *maximal regularity*, use the *implicit function theorem* to obtain local well-posedness of the nonlinear problem.

Use a variant of ANGENENT'S *parameter trick* to obtain real analyticity via *maximal regularity* and the *implicit function theorem*; cf. ESCHER, PRÜSS & SIMONETT 2003.

## Theorem

- (a)  $f_v \in L_p(J \times \Omega)^n$ ,  $v_0 \in W_p^{2-2/p}(\Omega \setminus \Sigma)^n$ ,  $v_0 = 0$  on  $\partial\Omega$ ;
- (b)  $f_d \in H_p^1(J; H_p^{-1}(\Omega \setminus \Sigma)) \cap L_p(J; H_p^1(\Omega \setminus \Sigma))$ ,  $\operatorname{div} v_0 = f_d(0)$ ;
- (c)  $g \in W_p^{1/2-1/2p}(J; L_p(\Sigma)) \cap L_p(J; W_p^{1-1/p}(\Sigma))$ ;
- (d)  $[[v_0]] = 0$ ,  $\mathcal{P}_\Sigma[[\mu(\nabla v_0 + \nabla v_0^T)]] = g_v(0)$ ;
- (e)  $h_0 \in W_p^{3-2/p}(\Sigma)$ ;
- (f)  $g_h \in W_p^{1-1/2p}(J; L_p(\Sigma)) \cap L_p(J; W_p^{2-1/p}(\Sigma))$ .

The solution map  $(v_0, h_0, f, f_d, g, g_h) \mapsto (v, q, h)$  is continuous between the corresponding spaces.

### c) The Nonlinear Problem

Based on *maximal regularity*, use the *implicit function theorem* to obtain local well-posedness of the nonlinear problem.

Use a variant of ANGENENT'S *parameter trick* to obtain real analyticity via *maximal regularity* and the *implicit function theorem*; cf. ESCHER, PRÜSS & SIMONETT 2003.

# The Induced Semiflow

Recall that the closed  $C^2$ -hypersurfaces contained in  $\Omega$  form a  $C^2$ -manifold, which we denote by  $\mathcal{MH}^2$ . Charts are obtained via parametrization over a fixed hypersurface. As an ambient space for the phase-manifold  $\mathcal{PM}$  of the two-phase Navier-Stokes problem with surface tension we consider the product space  $C(\bar{\Omega})^n \times \mathcal{MH}^2$ . We define  $\mathcal{PM}$  as follows.

$$\mathcal{PM} :=$$

$$\{(u, \Gamma) \in C(\bar{\Omega})^n \times \mathcal{MH}^2 : u \in W_p^{2-2/p}(\Omega \setminus \Gamma)^n, \Gamma \in W_p^{3-2/p}, \\ \operatorname{div} u = 0 \text{ in } \Omega \setminus \Gamma, u = 0 \text{ on } \partial\Omega, \mathcal{P}_\Gamma \llbracket \mu E \rrbracket \nu_\Gamma = 0 \text{ on } \Gamma\}. \quad (4)$$

The charts for this manifold are obtained by the charts induced by  $\mathcal{MH}^2$ , followed by a HANZAWA transformation.



# The Induced Semiflow

Recall that the closed  $C^2$ -hypersurfaces contained in  $\Omega$  form a  $C^2$ -manifold, which we denote by  $\mathcal{MH}^2$ . Charts are obtained via parametrization over a fixed hypersurface. As an ambient space for the phase-manifold  $\mathcal{PM}$  of the two-phase Navier-Stokes problem with surface tension we consider the product space  $C(\bar{\Omega})^n \times \mathcal{MH}^2$ . We define  $\mathcal{PM}$  as follows.

$\mathcal{PM} :=$

$$\{(u, \Gamma) \in C(\bar{\Omega})^n \times \mathcal{MH}^2 : u \in W_p^{2-2/p}(\Omega \setminus \Gamma)^n, \Gamma \in W_p^{3-2/p}, \\ \operatorname{div} u = 0 \text{ in } \Omega \setminus \Gamma, u = 0 \text{ on } \partial\Omega, \mathcal{P}_\Gamma \llbracket \mu E \rrbracket \nu_\Gamma = 0 \text{ on } \Gamma\}. \quad (4)$$

The charts for this manifold are obtained by the charts induced by  $\mathcal{MH}^2$ , followed by a HANZAWA transformation.

Observe that the compatibility conditions

$$\begin{aligned} \operatorname{div} u &= 0 \text{ in } \Omega \setminus \Gamma, \quad u = 0 \text{ on } \partial\Omega, \\ \mathcal{P}_\Gamma \mu [(\nabla u + \nabla u^\top)] \nu_\Gamma &= 0, \quad [[u]] = 0 \quad \text{on } \Gamma, \end{aligned}$$

as well as regularity are preserved by the solutions.  
This yields the following result

### Theorem

*Let  $p > n + 2$ . Then the two-phase Navier-Stokes problem with surface tension generates a local semiflow on the phase-manifold  $\mathcal{P}\mathcal{M}$ . Each solution  $(u, \Gamma)$  exists on a maximal time interval  $[0, t_*)$ .*

# The energy functional and equilibria

Define the *energy functional* by means of

$$\Phi(u, \Gamma) := \frac{1}{2} \|\rho^{1/2} u\|_{L_2(\Omega)}^2 + \sigma \operatorname{mes} \Gamma(t).$$

Then

$$\partial_t \Phi(u, \Gamma) + 2 \|\mu^{1/2} E\|_{L_2(\Omega)}^2 = 0,$$

hence the energy functional is a Ljapunov functional, even a strict one.

## Proposition

Let  $\rho_i, \mu_i, \sigma > 0$  be constants. Then

- (a) The **energy equality** is valid for smooth solutions.
- (b) The **equilibria** are zero velocities, constant pressures in the phase-components, the dispersed phase is a union of nonintersecting balls.
- (c) The **energy functional** is a strict Ljapunov-functional.
- (d) The **critical points** of the energy functional for constant phase volumes are precisely the equilibria.

# The Stability Result

Assuming, for simplicity, that the phases are connected, we denote by

$$\mathcal{E} := \{(0, S_R(x_0)) : x_0 \in \Omega, R > 0, S_R(x_0) \subset \Omega\}$$

the set of equilibria without boundary contact. Note that  $\mathcal{E}$  forms a real analytic manifold of dimension  $n + 1$ .

Fix any such equilibrium  $(0, \Sigma) \in \mathcal{E}$ . We consider the behaviour of the solutions near this steady state.

Here we have to use the *full linearization* of the problem at an equilibrium  $(0, \Sigma)$  i.e. at  $(u, h) = (0, 0)$ , and for this reason we have to replace  $\Delta_\Sigma$  in the linear problem (3) by

$$\mathcal{A}_\Sigma = H'_f(0) = \frac{n-1}{R^2} + \Delta_\Sigma.$$

It is well-known that  $\mathcal{A}_\Sigma$  is *selfadjoint*, *negative semidefinite* and has *compact resolvent* in  $L_2(\Sigma)$ ;  $\lambda_0 = 0$  is an eigenvalue of dimension  $n$ .

# The Stability Result

Assuming, for simplicity, that the phases are connected, we denote by

$$\mathcal{E} := \{(0, S_R(x_0)) : x_0 \in \Omega, R > 0, S_R(x_0) \subset \Omega\}$$

the set of equilibria without boundary contact. Note that  $\mathcal{E}$  forms a real analytic manifold of dimension  $n + 1$ .

Fix any such equilibrium  $(0, \Sigma) \in \mathcal{E}$ . We consider the behaviour of the solutions near this steady state.

Here we have to use the *full linearization* of the problem at an equilibrium  $(0, \Sigma)$  i.e. at  $(u, h) = (0, 0)$ , and for this reason we have to replace  $\Delta_\Sigma$  in the linear problem (3) by

$$\mathcal{A}_\Sigma = H'_f(0) = \frac{n-1}{R^2} + \Delta_\Sigma.$$

It is well-known that  $\mathcal{A}_\Sigma$  is *selfadjoint*, *negative semidefinite* and has *compact resolvent* in  $L_2(\Sigma)$ ;  $\lambda_0 = 0$  is an eigenvalue of dimension  $n$ .

## Theorem

The equilibrium  $(0, \Sigma)$  is stable in the sense that for each  $\varepsilon \in (0, \varepsilon_0]$  there exists  $\delta(\varepsilon) > 0$  such that for all initial values  $(u_0, \Gamma_0)$  subject to

$$\text{dist}_{W_p^{3-2/p}}(\Gamma_0, \Sigma) \leq \delta(\varepsilon) \quad \text{and} \quad \|u_0\|_{W_p^{2-2/p}(\Omega \setminus \Gamma_0)} \leq \delta(\varepsilon)$$

there exists a unique global solution  $(u(t), \Gamma(t))$  of the problem, and it satisfies

$$\text{dist}_{W_p^{3-2/p}}(\Gamma(t), \Sigma) \leq \varepsilon \quad \text{and} \quad \|u(t)\|_{W_p^{2-2/p}(\Omega \setminus \Gamma(t))} \leq \varepsilon, \quad t \geq 0.$$

Moreover, as  $t \rightarrow \infty$  each of these solutions  $(u(t), \Gamma(t))$  converges to a probably different equilibrium  $(0, \Sigma_\infty)$  in the same topology, i.e.

$$\lim_{t \rightarrow \infty} \left( \text{dist}_{W_p^{3-2/p}}(\Gamma(t), \Sigma_\infty) + \|u(t)\|_{W_p^{2-2/p}(\Omega \setminus \Gamma(t))} \right) = 0.$$

The convergence is at exponential rate.

# Sketch of the Proof

As a base space we use

$$X_0 = L_{p,\sigma}(\Omega)^n \times W_p^{2-1/p}(\Sigma),$$

and we set

$$\bar{X}_1 = W_p^2(\Omega \setminus \Sigma)^n \times W_p^{3-1/p}(\Sigma)$$

Define a closed linear operator in  $X_0$  by means of

$$A(v, h) = (-(\mu/\rho)\Delta v + \rho^{-1}\nabla q, -(v|_{\nu_\Sigma})),$$

with domain  $X_1 := D(A) \subset \bar{X}_1$

$$D(A) = \{(v, h) \in \bar{X}_1 \cap X_0 : v = 0 \text{ on } \partial\Omega, \llbracket v \rrbracket = 0 \text{ and} \\ \llbracket \mathcal{P}_\Sigma \mu(\nabla v + \nabla v^T)\nu_\Sigma \rrbracket = 0 \text{ on } \Sigma\}.$$

Here  $q \in \dot{W}_p^1(\Omega \setminus \Sigma)$  is determined as the solution of the *weak transmission problem*

$$(\rho^{-1}\nabla q | \nabla \phi)_{L_2} = ((\mu/\rho)\Delta v | \nabla \phi)_{L_2}, \quad \phi \in W_{p'}^1(\Omega), \\ \llbracket q \rrbracket = \llbracket \mu((\nabla v + \nabla v^T)\nu_\Sigma | \nu_\Sigma) \rrbracket + \sigma \mathcal{A}_\Sigma h \quad \text{on } \Sigma.$$

# Sketch of the Proof

As a base space we use

$$X_0 = L_{p,\sigma}(\Omega)^n \times W_p^{2-1/p}(\Sigma),$$

and we set

$$\bar{X}_1 = W_p^2(\Omega \setminus \Sigma)^n \times W_p^{3-1/p}(\Sigma)$$

Define a closed linear operator in  $X_0$  by means of

$$A(v, h) = (-(\mu/\rho)\Delta v + \rho^{-1}\nabla q, -(v|_{\nu_\Sigma})),$$

with domain  $X_1 := D(A) \subset \bar{X}_1$

$$D(A) = \{(v, h) \in \bar{X}_1 \cap X_0 : v = 0 \text{ on } \partial\Omega, \llbracket v \rrbracket = 0 \text{ and} \\ \llbracket \mathcal{P}_\Sigma \mu(\nabla v + \nabla v^T)\nu_\Sigma \rrbracket = 0 \text{ on } \Sigma\}.$$

Here  $q \in \dot{W}_p^1(\Omega \setminus \Sigma)$  is determined as the solution of the *weak transmission problem*

$$(\rho^{-1}\nabla q | \nabla \phi)_{L_2} = ((\mu/\rho)\Delta v | \nabla \phi)_{L_2}, \quad \phi \in W_{p'}^1(\Omega), \\ \llbracket q \rrbracket = \llbracket \mu((\nabla v + \nabla v^T)\nu_\Sigma | \nu_\Sigma) \rrbracket + \sigma \mathcal{A}_\Sigma h \quad \text{on } \Sigma.$$



Then with  $z = (v, h)$  and  $f = (f_v, g_h)$  as well as  $z_0 = (v_0, h_0)$ , system (3) can be rewritten as the abstract evolution equation

$$\dot{z} + Az = f, \quad t > 0, \quad z(0) = z_0, \quad (5)$$

provided  $f_d = 0$  and  $g = 0$ .

Since (3) has maximal  $L_p$ -regularity, the abstract problem (5) has maximal  $L_p$ -regularity, as well. In particular,  $-A$  generates an analytic  $C_0$ -semigroup in  $X_0$ .

We can show the following properties:

- (i) The set of equilibria  $\mathcal{E}$  is an  $(n + 1)$ -dimensional smooth manifold.
- (ii) The kernel  $N(A)$  is isomorphic to the tangent space  $T_{(0, \Sigma)} \mathcal{E}$ .
- (iii)  $N(A) \oplus R(A) = X_0$ , i.e. the eigenvalue  $\lambda_0 = 0$  of  $A$  is semi-simple.
- (iv)  $\sigma(A) \setminus \{0\} \subset \mathbb{C}_+$ , i.e. the semigroup  $e^{-At}|_{R(A)}$  is exponentially stable.

This allows for the use of the *generalized principle of linearized stability*, see PRÜSS, SIMONETT & ZACHER 2009, to prove the theorem.

Then with  $z = (v, h)$  and  $f = (f_v, g_h)$  as well as  $z_0 = (v_0, h_0)$ , system (3) can be rewritten as the abstract evolution equation

$$\dot{z} + Az = f, \quad t > 0, \quad z(0) = z_0, \quad (5)$$

provided  $f_d = 0$  and  $g = 0$ .

Since (3) has maximal  $L_p$ -regularity, the abstract problem (5) has maximal  $L_p$ -regularity, as well. In particular,  $-A$  generates an analytic  $C_0$ -semigroup in  $X_0$ .

We can show the following properties:

- (i) The set of equilibria  $\mathcal{E}$  is an  $(n + 1)$ -dimensional smooth manifold.
- (ii) The kernel  $N(A)$  is isomorphic to the tangent space  $T_{(0, \Sigma)}\mathcal{E}$ .
- (iii)  $N(A) \oplus R(A) = X_0$ , i.e. the eigenvalue  $\lambda_0 = 0$  of  $A$  is semi-simple.
- (iv)  $\sigma(A) \setminus \{0\} \subset \mathbb{C}_+$ , i.e. the semigroup  $e^{-At}|_{R(A)}$  is exponentially stable.

This allows for the use of the *generalized principle of linearized stability*, see PRÜSS, SIMONETT & ZACHER 2009, to prove the theorem.

# Global Existence and Convergence

There are basically two obstructions against global existence:

- **regularity**: the norms of either  $u(t)$  or  $\Gamma(t)$  become unbounded;
- **geometry**: the topology of the interface changes or the interface touches the boundary of  $\Omega$ .

Note that the *phase volumes* are conserved by the semiflow!

We say that a solution  $(u, \Gamma)$  satisfies a uniform ball condition, if there is a radius  $r > 0$  such that for each  $t \in [0, t_*)$  and at every point  $p \in \Gamma(t)$  we have

$$\bar{B}_r(p \pm r\nu_{\Gamma(t)}(p)) \cap \Gamma(t) = \{p\}.$$

Combining the above results, we obtain the following theorem on the asymptotic behavior of solutions.

### Theorem

Let  $p > n + 2$ . Suppose that  $(u, \Gamma)$  is a solution of the two-phase Navier-Stokes problem with surface tension on the maximal time interval  $[0, t_*)$ . Assume the following on  $[0, t_*)$ :

(i)  $\|u(t)\|_{W_p^{2-2/p}} + \|\Gamma(t)\|_{W_p^{3-2/p}} \leq M < \infty$ ;

(ii)  $(u, \Gamma)$  satisfies a uniform ball condition.

Then  $t_* = \infty$ , i.e. the solution exists globally, and it converges in  $\mathcal{PM}$  at exponential rate to an equilibrium  $(0, \Gamma_\infty) \in \mathcal{E}$ . The converse is also true.

The idea of the proof is as follows. Assuming (i) and (ii) we show that the solution is global. The energy is a strict Ljapunov functional, hence the limit set  $\omega(u, \Gamma)$  of a solution is contained in the set  $\mathcal{E}$  of equilibria. A compactness argument shows  $\omega(u, \Gamma) \neq \emptyset$ , hence the solution comes close to  $\mathcal{E}$ . Then we may apply the local convergence result.

Combining the above results, we obtain the following theorem on the asymptotic behavior of solutions.

### Theorem

Let  $p > n + 2$ . Suppose that  $(u, \Gamma)$  is a solution of the two-phase Navier-Stokes problem with surface tension on the maximal time interval  $[0, t_*)$ . Assume the following on  $[0, t_*)$ :

(i)  $\|u(t)\|_{W_p^{2-2/p}} + \|\Gamma(t)\|_{W_p^{3-2/p}} \leq M < \infty$ ;

(ii)  $(u, \Gamma)$  satisfies a uniform ball condition.

Then  $t_* = \infty$ , i.e. the solution exists globally, and it converges in  $\mathcal{PM}$  at exponential rate to an equilibrium  $(0, \Gamma_\infty) \in \mathcal{E}$ . The converse is also true.

The idea of the proof is as follows. Assuming (i) and (ii) we show that the solution is global. The energy is a strict Ljapunov functional, hence the limit set  $\omega(u, \Gamma)$  of a solution is contained in the set  $\mathcal{E}$  of equilibria. A compactness argument shows  $\omega(u, \Gamma) \neq \emptyset$ , hence the solution comes close to  $\mathcal{E}$ . Then we may apply the local convergence result.