

# The spin-coating process and two-phase flow for generalized Newtonian fluids



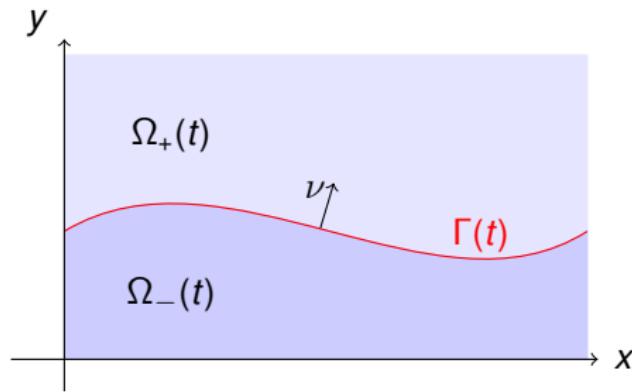
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joint work with Manuel Nesensohn (TU Darmstadt)

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# Setting for the two-phase flow problem

- ▶ two fluids occupying the whole space  $\mathbb{R}^n = \Omega_+(t) \cup \Omega_-(t) \cup \Gamma(t)$
- ▶ separated by a sharp interface  $\Gamma(t) = \{(x, y) \in \mathbb{R}^n : y = h(t, x)\}$



# Model equations

- ▶ model equations

$$\begin{aligned}\rho(\partial_t u + u \cdot \nabla u) - 2 \operatorname{div} \mu(|Du|^2) Du + \nabla \pi &= -\rho \gamma_a e_{n+1} && \text{in } \Omega(t) \\ \operatorname{div} u &= 0 && \text{in } \Omega(t)\end{aligned}$$

- |                           |                            |
|---------------------------|----------------------------|
| ▶ $u$ velocity            | ▶ $\rho$ density           |
| ▶ $Du$ deformation tensor | ▶ $\mu$ viscosity function |
| ▶ $\pi$ pressure          | ▶ $\gamma_a$ gravity       |

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- $u$  velocity
- $Du$  deformation tensor
- $\pi$  pressure
- $\rho$  density
- $\mu$  viscosity function
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# Nonlinear diffusion term

- ▶ introduce quasilinear operator  $\mathcal{A}$

$$\mathcal{A}(u)v = \sum_{j,l=1}^n A^{j,l}(Du)\partial_k\partial_l v$$

- ▶  $A^{j,l}_{i,k}(X) = \mu(|X|^2)\delta_{i,k}\delta_{j,l} + \mu'(|X|^2)X_{ik}X_{jl}$
- ▶ then  $\mathcal{A}(u)u = -2 \operatorname{div} \mu(|Du|^2)Du$  and  $\mathcal{A}(0)u = -\mu(0)\Delta u$

# Main result (two-phase flow)

## Assumptions:

- ▶  $n + 2 < p < \infty$
- ▶  $\mu \in C^3$  with  $\mu(0) > 0$
- ▶  $u_0 \in W_p^{2-2/p}$ ,  $h_0 \in W_p^{3-2/p}$  satisfying suitable compatibility conditions

For all  $T > 0$  there exists  $\varepsilon > 0$  such that for

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there exists a unique solution  $(u, \pi, h)$  on  $(0, T)$  in

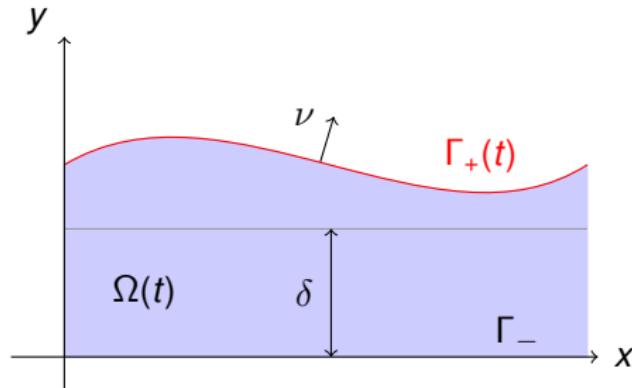
$$u \in H_p^1(L_p) \cap L_p(H_p^2),$$

$$\pi \in \{q \in L_p(\widehat{H}_p^1) : \llbracket q \rrbracket \in W_p^{1/2-1/2p}(L_p) \cap L_p(W_p^{1-1/p})\},$$

$$h \in W_p^{2-1/2p}(L_p) \cap W_p^1(W_p^{2-1/p}) \cap L_p(W_p^{3-1/p}).$$

# Setting for the spin-coating problem

- ▶ a fluid is applied to the center of a spinning plate and is assumed to occupy a domain  $\Omega(t)$  close to a layer
- ▶ the bottom boundary is a fixed plane  $\Gamma_-$
- ▶ the upper boundary is a free surface initially close to a plane  $\Gamma_+(t) = \{(x, y) \in \mathbb{R}^n : y = \delta + h(t, x)\}$ ,  $\delta > 0$



# Model equations

- ▶ model equations for  $u = (v, w)$ ,  $n = 3$

$$\begin{aligned} \rho(\partial_t u + u \cdot \nabla u) + \mathcal{A}(u)u + \nabla \pi &= -\rho(2\omega \times u + \omega \times (\omega \times \chi_R(x)(x, y))) && \text{in } \Omega(t) \\ \operatorname{div} u &= 0 && \text{in } \Omega(t) \end{aligned}$$

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# Known Results

## Two-phase flow

- ▶ Prüss, Simonett - constant viscosity:
  - '09 detailed investigation of the mapping properties of the boundary symbol
  - '10 solvability of the linear and nonlinear problems (small data)
  - t.a. solvability of the linear and nonlinear problems with gravity (large data)
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## Spin-Coating

- ▶ Denk, Geissert, Hieber, Saal, Sawada:
  - '11 same setting for Newtonian fluids

# Short sketch of proof I

- ▶ Hanzawa transform onto a fixed reference domain

$$(t, x, y) \rightarrow (t, x, y + h(t, x)) \quad (t, x, y) \rightarrow \left( t, x, y \frac{h(t, x) + \delta}{\delta} \right)$$

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- ▶ receive error terms for derivatives

$$\begin{aligned} Du &\rightarrow D\bar{u} - F_D(\partial_y \bar{u}, \nabla' h), \\ \nabla \pi &\rightarrow \nabla \bar{\pi} - F_\pi(\partial_y \bar{\pi}, \nabla h), \\ \operatorname{div} u &\rightarrow \operatorname{div} \bar{u} - F_d(\bar{u}, h), \quad \text{etc.} \end{aligned}$$

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- ▶ the kinematic condition  $V = (u|\nu)$  transforms to

$$\partial_t h + (\nabla' h | \nu) = w$$

# Transformed system

- ▶ nonlinear transformed system (in the case of the two-phase flow)

$$\begin{aligned}\rho \partial_t u - \mu(0) \Delta u + \nabla \pi &= F_f(u, \pi, h) && \text{in } \dot{\mathbb{R}}^n \\ \operatorname{div} u &= F_d(u, h) && \text{in } \dot{\mathbb{R}}^n \\ \partial_t h - w &= H(u, h) && \text{on } \mathbb{R}^{n-1} \\ -[\![\mu(0) \partial_y v]\!] - [\![\mu(0) \nabla' w]\!] &= G_v(u, [\![\pi]\!], h) && \text{on } \mathbb{R}^{n-1} \\ -2[\![\mu(0) \partial_y w]\!] + [\![\pi]\!] - [\![\rho]\!] \gamma_a h - \sigma \Delta h &= G_w(u, h) && \text{on } \mathbb{R}^{n-1} \\ [\![u]\!] &= 0 && \text{on } \dot{\mathbb{R}}^n \\ u(0) &= u_0 && \text{in } \dot{\mathbb{R}}^n \\ h(0) &= h_0 && \text{on } \mathbb{R}^{n-1}\end{aligned}$$

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$$\begin{aligned}\rho \partial_t u - \mu(0) \Delta u + \nabla \pi &= f && \text{in } \dot{\mathbb{R}}^n \\ \operatorname{div} u &= f_d && \text{in } \dot{\mathbb{R}}^n \\ \partial_t h - w &= f_h && \text{on } \mathbb{R}^{n-1} \\ -[\![\mu(0) \partial_y v]\!] - [\![\mu(0) \nabla' w]\!] &= g_v && \text{on } \mathbb{R}^{n-1} \\ -2[\![\mu(0) \partial_y w]\!] + [\![\pi]\!] - [\![\rho]\!] \gamma_a h - \sigma \Delta h &= g_w && \text{on } \mathbb{R}^{n-1} \\ [\![u]\!] &= 0 && \text{on } \mathbb{R}^{n-1} \\ u(0) &= u_0 && \text{in } \dot{\mathbb{R}}^n \\ h(0) &= h_0 && \text{on } \mathbb{R}^{n-1}\end{aligned}$$

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- ▶ Prüß, Simonett/Denk, Geissert, Hieber, Saal, Sawada: there exists a well-defined continuous solution operator to the linearized system  $L^{-1} : \mathbb{F} \mapsto \mathbb{E}$  under certain compatibility conditions on the initial data

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Thank you for your attention.