Navier-Stokes Flow in Infinite Cylinders with Non-Constant Cross Section

Jonas Sauer Department of Mathematics Darmstadt University of Technology



Stokes resolvent problem

$$\begin{array}{rll} \lambda u - \Delta u + \nabla p &= f & \text{ in } \Omega, \\ \text{div } u &= g & \text{ in } \Omega, & \text{ in } L^q \text{-setting } (\mathsf{R}) \\ u &= 0 & \text{ on } \partial \Omega, \end{array}$$



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 - $R(\varphi, z) \ge \delta > 0$ Lipschitz continuous



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$$\|\nabla' R\|_{\infty}, \|\nabla'^2 R\|_{\infty} < K \tag{K}$$



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with $\lambda \in -\alpha + \Sigma_{\theta}, \theta \in (\pi/2, \pi), \alpha \in (0, \alpha_0)$

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- $\Sigma \subset \mathbb{R}^2$: bounded $C^{1,1}$ -domain, star-shaped w.r.t. some ball around 0
 - α₀ > 0: smallest eigenvalue of the Dirichlet Laplacian in Σ





Theorem 1

- ▶ 2≤q<∞
- smallness assumption (K)
- $(f,g) \in L^q(\Omega)^3 \times \left(W^{1,q}(\Omega) \cap \hat{W}^{-1,q}(\Omega) \right)$



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► a priori estimate

$$\|(\lambda + \alpha)u, \nabla^2 u, \nabla p\|_q \le c(\|f\|_q + \|g\|_{1,q} + (|\lambda| + 1)\|g\|_{\dot{W}^{-1,q}(\Omega)})$$

• $c(q, \alpha, \theta, \Omega) > 0$ independent of λ



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H^{∞} -calculus



Definition

► sectorial operator *B* on Banach space *X* admits bounded $H^{\infty}(\Sigma_{\theta})$ -calculus if

 $\|h(B)\|_{\mathcal{L}(X)} \leq c \|h\|_{\infty}$

for all holomorphic and bounded functions on Σ_θ

• how to define $h(B) \rightsquigarrow$ Complex Analysis

$$h(B) := \frac{1}{2\pi i} \int_{\Gamma} h(\lambda) (\lambda - B)^{-1} d\lambda$$

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Theorem 2

For $1 < q < \infty$ the Stokes operator A_q admits a bounded $H^{\infty}(\Sigma_{\theta})$ -calculus in $L^q_{\sigma}(\Omega)$ for any $\theta \in (0, \pi)$.



Ingredients

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 - Since S is a isomorphism of Banach spaces, so are small perturbations by a Neumann series argument
- For 1 < q < 2, g = 0 use duality arguments for the Stokes operator.
- For domains with certain regularity properties such that 0 ∈ ρ(A_q), the Stokes operator admits a bounded H[∞](Σ_θ)-calculus by a result by Abels (2004).



Transformation back to the straight cylinder in cylindrical coordinates via

$$(\tilde{r}, \tilde{\varphi}, \tilde{z}) = \phi(r, \varphi, z) = \left(\frac{r}{P(\varphi, z)}, \varphi, z\right)$$

with $P(\varphi, z) = R(\varphi, z)/R(\varphi, 0)$.



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d

Transformed divergence

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$$u = \widetilde{\operatorname{div}} \tilde{u}$$

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- $\tilde{\partial}_r \tilde{u}_{\varphi} \left(\frac{\partial_{\varphi} P(\varphi, z)}{P(\varphi, z)^2}\right) - \tilde{r} \tilde{\partial}_r \tilde{u}_z \left(\frac{\partial_z P(\varphi, z)}{P(\varphi, z)}\right)$



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 $\blacktriangleright S(u,p) = (\lambda u - \Delta u + \nabla p, -\operatorname{div} u) \text{ is close to } \tilde{S}(\tilde{u}, \tilde{p}) = (\lambda \tilde{u} - \widetilde{\Delta} \tilde{u} + \widetilde{\nabla} \tilde{p}, -\widetilde{\operatorname{div}} \tilde{u})!$



Thank you very much for your attention!

Questions?